# On a Problem of G. G. Lorentz 

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DEDICATED TO GEORGE LORENTZ ON HIS 90TH BIRTHDAY

Let $C(B)$ denote the space of real-valued continuous functions on $B$. At the conference "Harmonic Analysis and Approximations" held at Nor Amberd in Armenia in September, 1998, the following general problem was posed by Professor George G. Lorentz: Find conditions on finite-dimensional subspaces $U$ and $V$ so that $U / V$ is a uniqueness set in the problem of best uniform approximation to elements of $C(B)$. In this paper we consider this problem. © 2000 Academic Press

## 1. INTRODUCTION

We first set some notation. For ease of exposition, assume $B$ is a finite union of connected compact components, none of which is a singleton, in $\mathbb{R}^{d}$ for some $d$. Let $C(B)$ denote the space of real-valued continuous functions on $B$. Let $U_{n}$ and $V_{m}$ be $n$ and $m$-dimensional linear subspaces of $C(B)$, respectively. We further assume that $V_{m}$ contains a function which is strictly positive on $B$. Set

$$
\frac{U_{n}}{V_{m}}=\left\{\frac{u}{v}: u \in U_{n}, v \in V_{m}, v>0\right\} .
$$

We are interested in the problem of when, to each $f$ in $C(B)$, we have at most one best approximant from the set $U_{n} / V_{m}$ in the uniform norm on $B$. This problem was posed by G. G. Lorentz in his talk at the conference "Harmonic Analysis and Approximations" at Nor Amberd in Armenia in September, 1998.

Before stating our main results let us recall some facts concerning "generalized rational approximation." In this setting it is not necessary that a best approximant from $U_{n} / V_{m}$ to each $f$ in $C(B)$ exist. However, it is always possible to characterize a best approximant if it does in fact exist.

Theorem 1.1 (Cheney and Loeb [5], Cheney [4]). Let $f \in C(B) . A$ necessary and sufficient condition for an element $r^{*}$ to be a best approximant to $f$ from $U_{n} / V_{m}$ is that the zero function be a best approximant to $f-r^{*}$ from the linear space $U_{n}+r^{*} V_{m}$ given by

$$
U_{n}+r^{*} V_{m}=\left\{u+r^{*} v: u \in U_{n}, v \in V_{m}\right\} .
$$

We are interested in the question of uniqueness of the best approximant, if it exists. On approximating from linear spaces (of finite dimension) the question of uniqueness, in the uniform norm, was considered by Haar [7]. He proved that for a $k$-dimensional approximating subspace $W_{k}$ of $C(B)$, the best approximant (which always exists) to each element of $C(B)$ is unique iff there does not exist a nontrivial $w \in W_{k}$ which vanishes at $k$ or more distinct points in $B$. As is more or less standard, we call linear spaces which have this property Haar spaces. (When $B=[a, b]$ the term Chebyshev space is more commonly used.)

Theorem 1.1 has the following consequence.
Proposition 1.2 (Cheney [3], Cheney [4]). If $r^{*}$ is a best approximant to $f \in C(B)$ from $U_{n} / V_{m}$ and if $U_{n}+r^{*} V_{m}$ is a Haar space, then $r^{*}$ is the unique best approximant to from $U_{n} / V_{m}$.

Thus a necessary condition that $U_{n} / V_{m}$ be a uniqueness set, i.e., each $f \in C(B)$ have at most one best approximant from $U_{n} / V_{m}$, is that $U_{n}+r^{*} V_{m}$ be a Haar space for every $r^{*} \in U_{n} / V_{m}$. The converse result need not quite hold in this generality only because our approximating set has the restriction that we only consider $u / v$ where $v$ is strictly of one sign on $B$.

Uniqueness of rational approximants is known in two cases. If $U_{n}$ and $V_{m}$ are algebraic polynomials of degree $n-1$ and $m-1$, respectively, and $B=[a, b]$, then uniqueness is due to Achieser [1] (see the more accessible Achieser [2]). If $U_{n}$ and $V_{m}$ are the analogous trigonometric polynomials then uniqueness, within the class of $2 \pi$-periodic continuous functions, was recently proved in Lorentz et al. [8, p. 217].

Before considering conditions under which $U_{n}+r^{*} V_{m}$ is a Haar space for every $r^{*}$ in $U_{n} / V_{m}$, let us first note some facts concerning the subspaces $U_{n}+r^{*} V_{m}$ and some necessary properties which are implied by the assumption that $U_{n}+r^{*} V_{m}$ is a Haar space for every $r^{*}$ in $U_{n} / V_{m}$.

Lemma 1.3. For each $r^{*} \in U_{n} / V_{m}$,

$$
\begin{equation*}
n \leqslant \operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) \leqslant n+m-1, \tag{1.1}
\end{equation*}
$$

and if $U_{n}$ and $V_{m}$ are Haar spaces, and $r^{*} \neq 0$, then we also have

$$
m \leqslant \operatorname{dim}\left(U_{n}+r^{*} V_{m}\right)
$$

Proof. The lower bound in (1.1) is a consequence of the fact that $U_{n} \subseteq U_{n}+r^{*} V_{m}$ for any $r^{*} \in U_{n} / V_{m}$. The perhaps somewhat surprising upper bound may be proven as follows. Let

$$
U_{n}=\operatorname{span}\left\{u_{1}, \ldots, u_{n}\right\}, \quad V_{m}=\operatorname{span}\left\{v_{1}, \ldots, v_{m}\right\},
$$

and $r^{*}=u^{*} / v^{*}$, where $u^{*}=\sum_{i=1}^{n} a_{i}^{*} u_{i}$ and $v^{*}=\sum_{i=1}^{m} b_{i}^{*} v_{i}, v^{*}>0$ on $B$. Then

$$
U_{n}+r^{*} V_{m}=\operatorname{span}\left\{u_{1}, \ldots, u_{n}, r^{*} v_{1}, \ldots, r^{*} v_{m}\right\} .
$$

The above $n+m$ functions which span $U_{n}+r^{*} V_{m}$ are linearly dependent since

$$
\sum_{i=1}^{n} a_{i}^{*} u_{i}-r^{*}\left(\sum_{i=1}^{m} b_{i}^{*} v_{i}\right)=u^{*}-\left(\frac{u^{*}}{v^{*}}\right) v^{*}=0 .
$$

Thus

$$
\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) \leqslant n+m-1 .
$$

Assume $U_{n}$ and $V_{m}$ are Haar spaces. This implies (since $B$ contains a continuum of points) that if $u \in U_{n}, v \in V_{m}$, and $u v=0$, then $u=0$ or $v=0$. From this property it follows that for $r^{*} \in U_{n} / V_{m}, r^{*} \neq 0$,

$$
m=\operatorname{dim}\left(r^{*} v_{1}, \ldots, r^{*} v_{m}\right)=\operatorname{dim}\left(r^{*} V_{m}\right) \leqslant \operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) .
$$

Proposition 1.4. If $U_{n}+r^{*} V_{m}$ is a Haar space for every $r^{*} \in U_{n} / V_{m}$, then $U_{n}$ and $V_{m}$ are themselves Haar spaces. The converse result holds if $n=1$ or $m=1$.

Proof. We set $r^{*}=0$ in $U_{n}+r^{*} V_{m}$ and deduce that $U_{n}$ is a Haar space.
Assume $V_{m}$ is not a Haar space. There then exists a $\tilde{v} \in V_{m}, \tilde{v} \neq 0$, that vanishes at at least $m$ distinct points of $B$. Given any $n-1$ points distinct from the above $m$ points, there exists a $u^{*} \in U_{n}, u^{*} \neq 0$, which vanishes thereon. Let $v^{*} \in V_{m}$ be strictly positive on $B$, and set $r^{*}=u^{*} / v^{*}$. Then

$$
r^{*} \tilde{v} \in r^{*} V_{m} \subseteq U_{n}+r^{*} V_{m},
$$

and $r^{*} \tilde{v} \neq 0$ has at least $n+m-1$ distinct zeros. Since $\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) \leqslant$ $n+m-1$, this contradicts the assumption that $U_{n}+r^{*} V_{m}$ is a Haar space.

Assume $U_{n}$ and $V_{m}$ are Haar spaces and $n=1$ or $m=1$. If $r^{*}=0$, then $U_{n}+r^{*} V_{m}=U_{n}$ is a Haar space. For $r^{*} \neq 0$ it follows from Lemma 1.3 that

$$
\max \{n, m\}=\operatorname{dim}\left\{U_{n}+r^{*} V_{m}\right\} .
$$

If $m=1$, then $U_{n}+r^{*} V_{1}=U_{n}$ is a Haar space. If $n=1\left(\right.$ and $\left.r^{*} \neq 0\right)$ then $r^{*}$ is strictly of one sign on $B\left(U_{1}\right.$ is a Haar space $)$ and $U_{1}+r^{*} V_{m}=r^{*} V_{m}$ is also a Haar space.

The converse result need not hold in general. That is, it may be that $U_{n}$ and $V_{m}$ are Haar spaces, while $U_{n}+r^{*} V_{m}$ is not a Haar space for some $r^{*}$ in $U_{n} / V_{m}, n, m \geqslant 2$. An example thereof may be found in Cheney [4, p. 169].

Set

$$
U_{n} V_{m}=\left\{u v: u \in U_{n}, v \in V_{m}\right\} .
$$

(By $u v$ we mean simple multiplication, i.e., $(u v)(x)=u(x) v(x)$.) Under relatively mild assumptions on $U_{n}$ and $V_{m}$ it may easily be shown that

$$
\operatorname{dim}\left(U_{n} V_{m}\right) \geqslant n+m-1
$$

We will prove that if $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$ and $U_{n}, V_{m}$ are Haar spaces, then

$$
U_{n}+r^{*} V_{m}
$$

is a Haar space for every $r^{*}$ in $U_{n} / V_{m}$. This is one of the main result of this paper.

Theorem 1.5. If $U_{n}$ and $V_{m}$ are Haar spaces in $C(B)$ and

$$
\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1
$$

then $U_{n} / V_{m}$ is a uniqueness set (and $U_{n} V_{m}$ is a Haar space).
This condition implying uniqueness (and also existence) is neither fortuitous nor unexpected. Consider $r^{*}=u^{*} / v^{*} \in U_{n} / V_{m}$. Then

$$
u+r^{*} v=\frac{u v^{*}+u^{*} v}{v^{*}}
$$

By assumption $v^{*}$ does not vanish on $B$. Thus the zero sets of $u+r^{*} v$ and $u v^{*}+u^{*} v$ are identical and the latter function is contained in $U_{n} V_{m}$. Since we are interested in conditions implying that $U_{n}+r^{*} V_{m}$ is a Haar space, and since $\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) \leqslant n+m-1$, it is thus natural to consider when $U_{n} V_{m}$ is a Haar space of dimension $n+m-1$.

Note that sums of the form $u v^{*}+u^{*} v$ are a manifold within $U_{n} V_{m}$. The two restrictions are that $v^{*}$ be strictly of one sign on $B$, and that we only permit the sum of two products (rather than $\min \{n, m\}$ products which are in general necessary to span $U_{n} V_{m}$ ).

The demand that $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$ is very stringent. Theorem 1.5 is a consequence of the following. Assume that $U_{n}$ and $V_{m}$ have the property that

$$
\begin{equation*}
B=\overline{\operatorname{supp}\{g\}} \tag{1.2}
\end{equation*}
$$

for every nonzero $g$ in $U_{n}$ or $V_{m}(\operatorname{supp}\{g\}=\{x: g(x) \neq 0\})$. This property holds in particular if $U_{n}$ and $V_{m}$ are Haar spaces.

Theorem 1.6. Let $U_{n}$ and $V_{m}$ be $n$ - and m-dimensional subspaces of $C(B), n, m \geqslant 2$. Assume that (1.2) holds. Then $\operatorname{dim}\left(U_{n} V_{m}\right) \geqslant n+m-1$. Furthermore $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$ if and only if there exist $w_{1}, w_{2} \in C(B)$ and a function h defined on $B$ such that

$$
\begin{align*}
U_{n} & =\operatorname{span}\left\{w_{1} h^{i-1}: i=1, \ldots, n\right\}  \tag{1.3}\\
V_{m} & =\operatorname{span}\left\{w_{2} h^{i-1}: i=1, \ldots, m\right\} \tag{1.4}
\end{align*}
$$

Remark. In the statement of Theorem 1.6 we do not demand that $h$ be continuous. We will show, by example, that $h$ need not be continuous and sometimes cannot possibly be continuous. However as $w_{1} h^{i-1} \in U_{n} \subset C(B)$, for $i=1, \ldots, n$, and $w_{2} h^{i-1} \in V_{m} \subset C(B)$, for $i=1, \ldots, m$, the function $h$ must be continuous at those points where either $w_{1}$ or $w_{2}$ is nonzero.

Theorem 1.6, where $U_{n}=V_{m}$, was proven by Granovsky [6]. In fact he had fewer restrictions on both $B$ and $U_{n}$. His motivation for considering this problem came from questions in mathematical statistics connected with regression functions and the theory of experimental design.

## 2. PROOF OF THEOREM 1.6

If (1.3) and (1.4) hold, then $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$. It is the converse direction which we must labour to prove. Since that proof is somewhat lengthy, we will divide it into a series of steps.

Before embarking on these steps, let us note that Theorem 1.6 is not valid without some conditions on $U_{n}$ and $V_{m}$. For example, assume $U_{3}=$ $V_{3}=\operatorname{span}\{1, x,|x|\}$ on $[-1,1]$. Then $\operatorname{dim}\left(U_{3} U_{3}\right)=5$ and yet $U_{3}$ is not of the desired form. Similarly if $U_{n}$ contains $n$ functions with disjoint support, then $\operatorname{dim}\left(U_{n} U_{n}\right)=n$. (Note that in both examples there exist nonzero $u_{1}, u_{2} \in U_{n}$ for which $u_{1} u_{2}=0$, see Granovsky [6].)

In the proof of Theorem 1.6 we follow, with some modifications, the basic form of the proof as given in Granovsky [6].

Let us assume that $n \geqslant m \geqslant 2$. We start by choosing distinct points $x_{1}, \ldots, x_{n}$ in $B$ for which

$$
\begin{equation*}
\left.\operatorname{dim} U_{n}\right|_{\left\{x_{1}, \ldots, x_{n}\right\}}=n \tag{2.1}
\end{equation*}
$$

and such that

$$
\begin{equation*}
\left.\operatorname{dim} V_{m}\right|_{\left\{x_{11}, \ldots, x_{i_{m}}\right\}}=m \tag{2.2}
\end{equation*}
$$

for every choice of distinct $\left\{i_{1}, \ldots, i_{m}\right\} \subseteq\{1, \ldots, n\}$. That such a choice of $\left\{x_{1}, \ldots, x_{n}\right\}$ exists follows from our assumption concerning the form of $B$, $U_{n}$ and $V_{m}$.

Let $p_{i} \in U_{n}, i=1, \ldots, n$, satisfy

$$
\begin{equation*}
p_{i}\left(x_{k}\right)=\delta_{i k}, \quad i, k=1, \ldots, n \tag{2.3}
\end{equation*}
$$

Such $p_{i}$ exist and form a basis for $U_{n}$ as a consequence of (2.1). Let $q_{j} \in V_{m}$, $j=1, \ldots, m$, satisfy

$$
\begin{equation*}
q_{j}\left(x_{k}\right)=\delta_{j k}, \quad j, k=1, \ldots, m \tag{2.4}
\end{equation*}
$$

From (2.2) such $q_{j}$ exist and form a basis for $V_{m}$. Furthermore from (2.2),

$$
\begin{equation*}
q_{j}\left(x_{k}\right) \neq 0, \quad j=1, \ldots, m, \quad k=m+1, \ldots, n \tag{2.5}
\end{equation*}
$$

Lemma 2.1. The $n+m-1$ functions $p_{1} q_{1}, p_{2} q_{2}, \ldots, p_{m} q_{m}, p_{2} q_{1}, \ldots, p_{n} q_{1}$ are linearly independent.

Proof. Assume

$$
\begin{equation*}
\sum_{j=1}^{m} \beta_{j} p_{j} q_{j}+\left(\sum_{i=2}^{n} \alpha_{i} p_{i}\right) q_{1}=0 \tag{2.6}
\end{equation*}
$$

Evaluate the left-hand side of (2.6) at the points $x_{k}, k=1, \ldots, m$, to obtain (using (2.3) and (2.4))

$$
\beta_{k}=0, \quad k=1, \ldots, m
$$

Thus (2.6) reduces to

$$
\left(\sum_{i=2}^{n} \alpha_{i} p_{i}\right) q_{1}=0
$$

From our assumption (1.2) on $B, U_{n}$, and $V_{m}$, if $u v=0, u \in U_{n}, v \in V_{m}$, then $u=0$ or $v=0$. Thus either $q_{1}=0$ (which is simply not true), or

$$
\sum_{i=2}^{n} \alpha_{i} p_{i}=0
$$

As the $p_{2}, \ldots, p_{n}$ are linearly independent, this implies that $\alpha_{2}=\ldots=$ $\alpha_{n}=0$.

From Lemma 2.1 it follows that $\operatorname{dim}\left(U_{n} V_{m}\right) \geqslant n+m-1$. Since

$$
U_{n} V_{m}=\operatorname{span}\left\{p_{k} q_{\ell}: k=1, \ldots, n, \ell=1, \ldots, m\right\}
$$

Lemma 2.1 further implies that $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$ if and only if each $p_{k} q_{\ell}$ is a linear combination of the $n+m-1$ functions in the statement of Lemma 2.1, i.e., $p_{i} q_{j}$ satisfying $i=j$ or $j=1$. We assume in what follows in this section that $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$.

Lemma 2.2. For each $k, \ell, s$, satisfying $k \neq \ell, k=1, \ldots, n, \ell, s=1, \ldots, m$, there exist constants $\alpha_{k, \ell}^{s}, \beta_{k, \ell}^{s}$ for which

$$
\begin{equation*}
p_{k} q_{\ell}=\left(\alpha_{k, \ell}^{s} p_{k}+\beta_{k, \ell}^{s} p_{\ell}\right) q_{s} . \tag{2.7}
\end{equation*}
$$

Proof. It suffices to prove (2.7) for $s=1$. (The choice of $q_{1}$ here and in Lemma 2.1 is arbitrary and it may be replaced by $q_{s}$ for any $s=1, \ldots, m$.)

From Lemma 2.1 we have $\left(\right.$ since $\left.\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1\right)$,

$$
\begin{equation*}
p_{k} q_{\ell}=\left(\sum_{i=2}^{n} \gamma_{k, \ell}^{i} p_{i}\right) q_{1}+\sum_{j=1}^{m} \sigma_{k, \ell}^{j} p_{j} q_{j}, \tag{2.8}
\end{equation*}
$$

for some constants $\gamma_{k, \ell}^{i}$ and $\sigma_{k, \ell}^{j}$.
Assume $k \neq \ell$. We will first evaluate (2.8) at $x_{r}, r=1, \ldots, m$. Since $k \neq \ell$,

$$
p_{k}\left(x_{r}\right) q_{t}\left(x_{r}\right)=0, \quad r=1, \ldots, m
$$

and

$$
p_{i}\left(x_{r}\right) q_{1}\left(x_{r}\right)=0, \quad r=1, \ldots, m,
$$

for each $i=2, \ldots, n$. Furthermore

$$
p_{j}\left(x_{r}\right) q_{j}\left(x_{r}\right)=\delta_{r j}, \quad r, j=1, \ldots, m .
$$

Thus from (2.8) it follows that

$$
\sigma_{k, \ell}^{r}=0, \quad r=1, \ldots, m,
$$

and (2.8) reduces to

$$
\begin{equation*}
p_{k} q_{\ell}=\left(\sum_{i=2}^{n} \gamma_{k, \ell}^{i} p_{i}\right) q_{1} . \tag{2.9}
\end{equation*}
$$

We now evaluate (2.9) at $x_{r}, r=m+1, \ldots, n$. By construction

$$
p_{k}\left(x_{r}\right) q_{t}\left(x_{r}\right)=\delta_{k r} q_{t}\left(x_{r}\right),
$$

and from (2.5), $q_{t}\left(x_{r}\right) \neq 0$ for $r=m+1, \ldots, n$. Similarly

$$
\left(\sum_{i=2}^{n} \gamma_{k, \ell}^{i} p_{i}\right)\left(x_{r}\right)=\gamma_{k, \ell}^{r},
$$

(while $q_{1}\left(x_{r}\right) \neq 0$ ). Thus for $k \neq r, r=m+1, \ldots, n$, we have

$$
\gamma_{k, \ell}^{r}=0 .
$$

We may therefore rewrite (2.9) as

$$
\begin{equation*}
p_{k} q_{\ell}=\left(\sum_{i=2}^{m} \gamma_{k, \ell}^{i} p_{i}\right) q_{1} \tag{2.10}
\end{equation*}
$$

for $k \neq \ell$, and $k, \ell=1, \ldots, m$, and

$$
\begin{equation*}
p_{k} q_{\ell}=\left(\sum_{i=2}^{m} \gamma_{k, \ell}^{i} p_{i}+\gamma_{k, \ell}^{k} p_{k}\right) q_{1}, \tag{2.11}
\end{equation*}
$$

if $k=m+1, \ldots, n$. (Note that if $m=2$, then (2.10) and (2.11) are of the desired form.)
Choose $s \in\{1, \ldots, m\}, s \neq \ell$. We can replace $q_{\ell}$ by $q_{s}$ in (2.10) and (2.11) to obtain

$$
\begin{equation*}
p_{k} q_{s}=\left(\sum_{i=2}^{m} \gamma_{k, s}^{i} p_{i}\right) q_{1}, \tag{2.12}
\end{equation*}
$$

for $k \neq s$, and $k=1, \ldots, m$, and

$$
\begin{equation*}
p_{k} q_{s}=\left(\sum_{i=2}^{m} \gamma_{k, s}^{i} p_{i}+\gamma_{k, s}^{k} p_{k}\right) q_{1}, \tag{2.13}
\end{equation*}
$$

if $k=m+1, \ldots, n$.
Multiplying (2.10) by $q_{s}$ and (2.12) by $q_{\ell}$, it follows that for $k, \ell, s$ distinct in $\{1, \ldots, m\}$

$$
\left(\sum_{i=2}^{m} \gamma_{k, \ell}^{i} p_{i}\right) q_{1} q_{s}=\left(\sum_{i=2}^{m} \gamma_{k, s}^{i} p_{i}\right) q_{1} q_{\ell} .
$$

From our assumption (1.2) this implies

$$
\begin{equation*}
\left(\sum_{i=2}^{m} \gamma_{k, \ell}^{i} p_{i}\right) q_{s}=\left(\sum_{i=2}^{m} \gamma_{k, s}^{i} p_{i}\right) q_{\ell} . \tag{2.14}
\end{equation*}
$$

Evaluate (2.14) at $x_{s}$. As $q_{s}\left(x_{s}\right)=1$ and $q_{t}\left(x_{s}\right)=0$, we obtain

$$
\sum_{i=2}^{m} \gamma_{k, \ell}^{i} p_{i}\left(x_{s}\right)=0 .
$$

Since $p_{i}\left(x_{s}\right)=\delta_{i s}$, this implies that $\gamma_{k, \ell}^{s}=0$. This is valid for every $s$ distinct from $k$ and $\ell$ in $\{1, \ldots, m\}$. This proves (2.7).

We now assume that $k \in\{m+1, \ldots, n\}$. We multiply (2.11) by $q_{s}$ and (2.13) by $q_{\ell}, s \neq \ell$, and parallel the above analysis to again obtain (2.7).

Lemma 2.3. Fix $k$, $\ell$ in (2.7). The coefficients $\left(\alpha_{k, \ell}^{s}, \beta_{k, \ell}^{s}\right), s=1, \ldots, m$, are pairwise linearly independent, i.e., $\left(\alpha_{k, \ell}^{s}, \beta_{k, \ell}^{s}\right) \neq \gamma\left(\alpha_{k, \ell}^{r}, \beta_{k, \ell}^{r}\right)$ for any constant $\gamma$ and distinct $s, r$ in $\{1, \ldots, m\}$.

Proof. Assume to the contrary that

$$
\left(\alpha_{k, \ell}^{s}, \beta_{k, \ell}^{s}\right)=\gamma\left(\alpha_{k, \ell}^{r}, \beta_{k, \ell}^{r}\right)
$$

for some $\gamma$ and $s \neq r$. Then from (2.7)

$$
p_{k} q_{\ell}=\gamma\left(\alpha_{k, \ell}^{r} p_{k}+\beta_{k, \ell}^{r} p_{\ell}\right) q_{s}=\left(\alpha_{k, \ell}^{r} p_{k}+\beta_{k, \ell}^{r} p_{\ell}\right) q_{r} .
$$

This implies that either

$$
\gamma q_{s}-q_{r}=0
$$

or

$$
\alpha_{k, \ell}^{r} p_{k}+\beta_{k, \ell}^{r} p_{\ell}=0 .
$$

The first option is invalid since the $q_{k}$ are linearly independent. The second equation together with (2.7) implies that $p_{k} q_{\ell}=0$, which again is impossible.

We will fix the $k, \ell$ in (2.7). For convenience in what follows assume $k$, $\ell \in\{1, \ldots, m\}, k \neq \ell$, and set

$$
Z_{k \ell}=\left\{x: p_{k}(x) q_{\ell}(x)=0\right\} .
$$

Note that by our assumption (1.2) $\overline{B \backslash Z_{k \ell}}=B$. From (2.7) it follows that if $x \notin Z_{k \ell}$, then in addition to $p_{k}(x), q_{t}(x)$ not vanishing we also have $q_{s}(x) \neq 0$ and $\left(\alpha_{k, \ell}^{s} p_{k}+\beta_{k, \ell}^{s} p_{\ell}\right)(x) \neq 0$ for each $s=1, \ldots, m$. On $B \backslash Z_{k \ell}$, set

$$
\begin{align*}
& h(x)=\frac{p_{\ell}(x)}{p_{k}(x)},  \tag{2.15}\\
& \Delta_{s}(x)=\alpha_{k, \ell}^{s}+\beta_{k, \ell}^{s} h(x), \quad s=1, \ldots, m, \tag{2.16}
\end{align*}
$$

and

$$
\begin{equation*}
w_{2}(x)=\frac{q_{t}(x)}{\prod_{s=1}^{m} \Delta_{s}(x)} . \tag{2.17}
\end{equation*}
$$

From (2.7) we have

$$
\begin{equation*}
q_{s}(x)=\frac{q_{t}(x)}{\Delta_{s}(x)} . \tag{2.18}
\end{equation*}
$$

Each of these quantities is well defined and continuous on $B \backslash Z_{k \epsilon}$. In fact neither $\Delta_{s}(x)$ nor $w_{2}(x)$ vanish on $B \backslash Z_{k t}$.

## Lemma 2.4. We have

$$
V_{m}=\operatorname{span}\left\{w_{2} h^{i-1}: i=1, \ldots, m\right\} .
$$

Proof. We first restrict ourselves to $B \backslash Z_{k t}$. If $v \in V_{m}$, then since the $\left\{q_{s}\right\}_{s=1}^{m}$ span $V_{m}$ and from (2.17) and (2.18)

$$
\begin{aligned}
v(x) & =\sum_{s=1}^{m} a_{s} q_{s}(x)=\sum_{s=1}^{m} a_{s} \frac{q_{\epsilon}(x)}{\Delta_{s}(x)} \\
& =\frac{q_{\ell}(x)}{\prod_{s=1}^{m} \Delta_{s}(x)} \sum_{s=1}^{m} \alpha_{s}\left(\prod_{\substack{r=1 \\
r \neq s}}^{m} \Delta_{r}(x)\right) \\
& =w_{2}(x) \sum_{s=1}^{m} a_{s}\left(\prod_{\substack{r=1 \\
r \neq s}}^{s} \Delta_{r}(x)\right),
\end{aligned}
$$

for $x \in B \backslash Z_{k \ell}$. The expression

$$
\prod_{\substack{r=1 \\ r \neq s}}^{m} \Delta_{r}(x)=\prod_{\substack{r=1 \\ r \neq s}}^{m}\left(\alpha_{k, \ell}^{r}+\beta_{k, \ell}^{r} h(x)\right)
$$

is a polynomial of degree at most $m-1$ in $h$. Thus on $B \backslash Z_{k t}$

$$
v=w_{2} \sum_{i=1}^{m} \gamma_{i} h^{i-1} .
$$

It is easily shown, using Lemma 2.3, that

$$
\operatorname{span}\left\{\prod_{\substack{r=1 \\ r \neq s}}^{m} \Delta_{r}(x): s=1, \ldots, m\right\}=\operatorname{span}\left\{h^{i-1}: i=1, \ldots, m\right\} .
$$

Thus the $w_{2} h^{i-1}, i=1, \ldots, m$, span $V_{m}$ on $B \backslash Z_{k \ell}$. These functions are linearly independent on $B \backslash Z_{k \ell}$ since otherwise there exists a nontrivial element of $V_{m}$ which identically vanishes on $B \backslash Z_{k \ell}$. This contradicts (1.2).

Since each $w_{2} h^{i-1} \in V_{m}$ and $V_{m} \subset C(B)$, it follows from our assumption (1.2) that each of these functions can be uniquely extended from $B \backslash Z_{k \ell}$ to $B$ as elements in $C(B)$. This proves the lemma.

The function $w_{2}$ is well defined on all of $B$. It is, after all, a function in $C(B)$ and $V_{m}$. This is not true of $h$, which is a ratio of two functions in $C(B)$ (and $V_{m}$ ). The function $h$ is continuous at every point where $w_{2}$ does not vanish, which includes $B \backslash Z_{k \ell}$, but it need not be continuous on all of $B$. Nonetheless, since $w_{2} h^{i-1}$ is continuous on all of $B$, this restricts the permissible types of discontinuities of $h$.

What we have done for $V_{m}$ we can also do for $U_{n}$.

Lemma 2.5. For each $k, \ell, s$, satisfying $k \neq \ell, k, \ell=1, \ldots, m, s=1, \ldots, n$, there exist constants $\gamma_{k, \ell}^{s}, \sigma_{k, \ell}^{s}$ for which

$$
\begin{equation*}
p_{k} q_{\ell}=p_{s}\left(\gamma_{k, \ell}^{s} q_{k}+\sigma_{k, t}^{s} q_{\ell}\right) . \tag{2.19}
\end{equation*}
$$

Furthermore the coefficients $\left(\gamma_{k, \ell}^{s}, \sigma_{k, \ell}^{s}\right), s=1, \ldots, n$, are pairwise linearly independent.

Proof. Rather than parallel our previous analysis we will show how (2.19) follows from (2.7).

We recall that (2.7) has the form

$$
p_{k} q_{\ell}=\left(\alpha_{k, \ell}^{s} p_{k}+\beta_{k, \ell}^{s} p_{\ell}\right) q_{s},
$$

for $k \neq \ell, k=1, \ldots, n, \ell, s=1, \ldots, m$. We can rewrite this as

$$
\beta_{k, \ell}^{s} p_{\ell} q_{s}=p_{k}\left(q_{\ell}-\alpha_{k, \ell}^{s} q_{s}\right) .
$$

Note that $\beta_{k, \ell}^{\ell}=0$ and thus $\beta_{k, \ell}^{s} \neq 0$ for $s \neq \ell$. As such we have

$$
p_{\ell} q_{s}=p_{k}\left(\gamma_{\ell, s}^{k} q_{\ell}+\sigma_{\ell, s}^{k} q_{s}\right)
$$

for all $k, \ell, s$ satisfying $k=1, \ldots, n, k \neq \ell$, and $s \neq \ell$. For $k=\ell$, set $\gamma_{\ell, s}^{k}=0$ and $\sigma_{\ell, s}^{k}=1$. We now simply rename $\ell, s$, and $k$ as $k, \ell$, and $s$, respectively, to obtain (2.19).

Paralleling the proof of Lemma 2.3, it follows that the $\left(\gamma_{k, \ell}^{s}, \sigma_{k, \ell}^{s}\right)$ are pairwise linearly independent, $s=1, \ldots, n$.

As previously, on $B \backslash Z_{k \ell}$ (recall that we chose $k, \ell \in\{1, \ldots, m\}, k \neq \ell$ ) set

$$
\begin{aligned}
& H(x)=\frac{q_{k}(x)}{q_{\ell}(x)} \\
& \Sigma_{s}(x)=\gamma_{k, \ell}^{s} H(x)+\sigma_{k, \ell}^{s}, \quad s=1, \ldots, n,
\end{aligned}
$$

and

$$
W_{1}(x)=\frac{p_{k}(x)}{\prod_{s=1}^{n} \Sigma_{s}(x)} .
$$

From (2.19) we have

$$
p_{s}(x)=\frac{p_{k}(x)}{\Sigma_{s}(x)} .
$$

Note that from (2.19) and the definition of $Z_{k \ell}$, each of these quantities is well defined and continuous on $B \backslash Z_{k t}$. Analogously to Lemma 2.4, we obtain

Lemma 2.6. We have

$$
U_{n}=\operatorname{span}\left\{W_{1} H^{i-1}: i=1, \ldots, n\right\} .
$$

Both $U_{n}$ and $V_{m}$, individually, have the desired form. But in one case we have multiplier $H$ and in the other case multiplier $h$. Our claim in Theorem 1.6 is that they are equal, or to be more precise, that they can be chosen to be equal. This we now prove.

We recall that $h=p_{\ell} / p_{k}$ and $H=q_{k} / q_{\ell}$. Take (2.7) with $s=k$, i.e.,

$$
p_{k} q_{\ell}=\left(\alpha_{k, \ell}^{k} p_{k}+\beta_{k, \ell}^{k} p_{\ell}\right) q_{k} .
$$

Divide by $p_{k} q_{\ell}$ (we restrict ourselves to $B \backslash Z_{k, \ell}$ ) to obtain

$$
1=\left(\alpha_{k, \ell}^{k}+\beta_{k, \ell}^{k} h\right) H,
$$

which implies

$$
\begin{equation*}
H=\frac{1}{\alpha_{k, \ell}^{k}+\beta_{k, \ell}^{k} h}\left(=\frac{1}{\Delta_{k}}\right) . \tag{2.20}
\end{equation*}
$$

Note that $\beta_{k, \ell}^{k} \neq 0$. Our desired result will follow from Lemma 2.7, which we state in a rather general form, as we will use it again.

Lemma 2.7. Let

$$
\begin{equation*}
W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\} \tag{2.21}
\end{equation*}
$$

be a $k$-dimensional subspace of $C(B), k \geqslant 2$. Assume $B=\overline{\operatorname{span}\{w\}}$ for every $w \in W_{k}, w \neq 0$. Let $a, b, c, d \in \mathbb{R}, a d-b c \neq 0$. Define the functions

$$
\begin{equation*}
G=\frac{a g+b}{c g+d}, \quad M=\frac{m(c g+d)^{k-1}}{(a d-b c)^{k-1}} . \tag{2.22}
\end{equation*}
$$

Then

$$
\begin{equation*}
W_{k}=\operatorname{span}\left\{M G^{i-1}: i=1, \ldots, k\right\} . \tag{2.23}
\end{equation*}
$$

Furthermore, if $W_{k}$ can be written in the forms (2.21) and (2.23) for some choices of $m, M, g$, and $G$, then (2.22) holds for some constants $a, b, c, d$ satisfying $a d-b c \neq 0$. That is, the $m$ and $g$ of $W_{k}$ are unique up to the above linear fractional transformation.

Proof. From $G=(a g+b) /(c g+d)$ it follows that $g=(d G-b) /$ $(-c G+a)$ and

$$
\begin{aligned}
m g^{i-1} & =m\left(\frac{d G-b}{-c G+a}\right)^{i-1}=\frac{m}{(-c G+a)^{k-1}}(d G-b)^{i-1}(-c G+a)^{k-1} \\
& =\frac{m(c g+d)^{k-1}}{(a d-b c)^{k-1}}(d G-b)^{i-1}(-c G+a)^{k-i} \\
& =M(d G-b)^{i-1}(-c G+a)^{k-i} .
\end{aligned}
$$

Each $(d G-b)^{i-1}(-c G+a)^{k-i}, i=1, \ldots, k$, is a polynomial in $G$ of degree at most $k-1$. Thus

$$
W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\} \subseteq \operatorname{span}\left\{M G^{i-1}: i=1, \ldots, k\right\} .
$$

Since $W_{k}$ is of dimension $k$ this implies equality, i.e., (2.23) holds.
Assume $W_{k}$ can be written in the form (2.21) and (2.23) for some choices of $m, M, g$, and $G$. Since $M, M G \in C(B)$ we mus have (from (2.21))

$$
\begin{equation*}
G=\frac{M G}{M} \in \frac{W_{k}}{W_{k}}=\frac{\sum_{i=1}^{k} \alpha_{i} g^{i-1}}{\sum_{i=1}^{k} \beta_{i} g^{i-1}} \tag{2.24}
\end{equation*}
$$

on $B \backslash Z$, where $Z$ is the union of the zero sets of $M$ and $m$. On this set the continuous functions $g$ and $G$ take on a continuum of values (since, for example, the zero set of $m(c-g) \in W_{k}$ is, by assumption, small for every constant $c$ ). As such we may regard the rightmost expression in (2.24) as
a rational function in $g$. We can factor out its common divisors and write it in the form

$$
G=\frac{\alpha \prod_{i=1}^{s}\left(g-\gamma_{i}\right)}{\prod_{j=1}^{t}\left(g-\delta_{j}\right)}
$$

for $s, t \leqslant k-1$, where $\gamma_{i} \neq \delta_{j}, i=1, \ldots, s, j=1, \ldots, t$, and $\alpha \in \mathbb{R}$. We wish to prove that $s, t \leqslant 1$. If $k=2$ we are finished. As such, assume $k>2$. Then

$$
G^{k-1}=\frac{M G^{k-1}}{M} \in \frac{W_{k}}{W_{k}}
$$

and

$$
\begin{equation*}
G^{k-1}=\frac{\alpha^{k-1} \prod_{i=1}^{s}\left(g-\gamma_{i}\right)^{k-1}}{\prod_{j=1}^{t}\left(g-\delta_{j}\right)^{k-1}} \tag{2.25}
\end{equation*}
$$

Since $g$ takes on a continuum of values and the rational function (2.25) is in irreducible form, it follows that this ratio is an element of $W_{k} / W_{k}$ if and only if $s, t \leqslant 1$.

Thus

$$
G=\frac{a g+b}{c g+d}
$$

for some constants $a, b, c, d$. If $a d-b c=0$, then $G$ is a constant function and (2.23) cannot hold. As such we must have $a d-b c \neq 0$.

We now consider $M$. Since

$$
M \in W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\},
$$

we have

$$
M=m\left(\sum_{i=1}^{k} \alpha_{i} g^{i-1}\right) .
$$

Similarly

$$
M G^{k-1}=m\left(\sum_{i=1}^{k} \alpha_{i} g^{i-1}\right)\left(\frac{a g+b}{c g+d}\right)^{k-1} \in W_{k}
$$

and so is also of the form

$$
m\left(\sum_{i=1}^{k} \beta_{i} g^{i-1}\right) .
$$

Thus

$$
\left(\frac{a g+b}{c g+d}\right)^{k-1}=\frac{\sum_{i=1}^{k} \beta_{i} g^{i-1}}{\sum_{i=1}^{k} \alpha_{i} g^{i-1}} .
$$

Since the left-hand side is irreducible in $g$, this implies that

$$
\sum_{i=1}^{k} \alpha_{i} g^{i-1}=\alpha(c g+d)^{k-1}
$$

for some constant $\alpha, \alpha \neq 0$. Thus

$$
M=m \alpha(c g+d)^{k-1} .
$$

To conclude the proof of Theorem 1.6 we now simply apply Lemma 2.7 to (2.20).

Remark. Assume

$$
W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\}
$$

as in the statement of Lemma 2.7. We know that $g$ is continuous where $m$ does not vanish. What happens at the zeros of $m$ ? If $m\left(x^{*}\right)=0$ then necessarily $\left(m g^{i-1}\right)\left(x^{*}\right)=0, i=1, \ldots, k-1$. It is, however, possible that $\left(m g^{k-1}\right)\left(x^{*}\right) \neq 0$, in which case $\lim _{x \rightarrow x^{*}}\left|g\left(x^{*}\right)\right|=\infty$.

Before returning to the question of uniqueness in rational approximation, let us consider the following question. Given a $k$-dimensional subspace $W_{k}$ of $C(B)$, how can we decide if $W_{k}$ is of the form

$$
W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\}
$$

for some $m$ and $g$. (We assume $B=\overline{\operatorname{supp}\{w\}}$ for every $w \in W_{k}, w \neq 0$.) It follows from Theorem 1.6 that $W_{k}$ has this form if and only if $\operatorname{dim}\left(W_{k} W_{k}\right)=2 k-1$. In the proof of Theorem 1.6 we made use of the functions $p_{i}$ and $q_{j}$. Here they are the same. It then follows from the proof of Theorem 1.6 (see (2.15)-(2.18)) that we can take $g=q_{1} / q_{2}$ and $m=q_{1} /\left(\prod_{s=1}^{k} \Delta_{s}\right)=q_{2} \cdots q_{k} / q_{1}^{k-2}$. As such we have:

Proposition 2.8. Let $W_{k}$ be a $k$-dimensional subspace of $C(B)$, and let $B=\overline{\operatorname{supp}\{w\}}$ for every $w \in W_{k}, w \neq 0$. Let $x_{1}, \ldots, x_{k}$ be distinct points in $B$ for which

$$
\left.\operatorname{dim} W_{k}\right|_{\left\{x_{1}, \ldots, x_{k}\right\}}=k
$$

and let $q_{i} \in W_{k}$ satisfy $q_{i}\left(x_{j}\right)=\delta_{i j}, i, j=1, \ldots, k$. Then

$$
W_{k}=\operatorname{span}\left\{m g^{i-1}: i=1, \ldots, k\right\}
$$

for some $m$ and $g$ if and only if

$$
\frac{q_{3} \cdots q_{k}}{q_{1}^{k-i-1} q_{2}^{i-2}} \in W_{k}, \quad i=1, \ldots, k
$$

Finally we note that Theorem 1.6 can be generalized to a product of any finite number of finite-dimensional subspaces.

Corollary 2.9. Let $U^{j}$ be an $n_{j}$-dimensional subspace of $C(B)$, $j=1, \ldots, r$. Assume that the properties of $B$ and the $U^{j}$ hold as in Theorem 1.6. Then $\operatorname{dim}\left(U^{1} \cdots U^{r}\right) \geqslant n_{1}+\cdots+n_{r}-(r-1)$. Furthermore $\operatorname{dim}\left(U^{1} \cdots U^{r}\right)=n_{1}+\cdots+n_{r}-(r-1)$ if and only if there exist $w_{j} \in C(B)$ and a function $h$ defined on $B$ such that

$$
U^{j}=\operatorname{span}\left\{w_{j} h^{i-1}: i=1, \ldots, n_{j}\right\}, \quad j=1, \ldots, r .
$$

## 3. PROOF OF THEOREM 1.5

In this section we return to a consideration of the problem of uniqueness in approximation from $U_{n} / V_{m}$. We prove Theorem 1.5. But we will in fact prove more than what is stated in Theorem 1.5.

We assume that $U_{n}$ and $V_{m}$ are Haar spaces of dimension $n$ and $m$, respectively, $n, m \geqslant 2$, in $C(B)$. (The cases where $n=1$ or $m=1$ are covered by Proposition 1.4.) Since $B$ is compact and $C(B)$ contains a Haar space of dimension $>1$, it follows from Mairhuber's Theorem (see Mairhuber [9]) that $B$ is topologically imbeddable in $S^{1}$ (the circle in $\mathbb{R}^{2}$ ) and if $n$ is even, this imbedding is into a strict subset of $S^{1}$. Our $B$ is somewhat more specific. As such, topological imbeddability is equivalent to the existence of a homeomorphism (continuous one-to-one map) between the appropriate sets. This means that we may consider $B$ as either a finite union of closed, disjoint intervals (none of which are singletons by our initial assumption) in $\mathbb{R}$, or as $S^{1}$, in which case both $n$ and $m$ are odd.

We first prove strengthened versions of Theorem 1.6.
Theorem 3.1. Let B be a finite union of closed, disjoint intervals of $\mathbb{R}$ (none of which are singletons). Assume $U_{n}$ and $V_{m}$ are $n$ - and m-dimensional Haar spaces in $C(B)$, respectively, $n, m \geqslant 2$, and $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$. Then we can write $U_{n}$ and $V_{m}$ in the form

$$
\begin{align*}
& U_{n}=\operatorname{span}\left\{w_{1} h^{i-1}: i=1, \ldots, n\right\}  \tag{3.1}\\
& V_{m}=\operatorname{span}\left\{w_{2} h^{i-1}: i=1, \ldots, m\right\} \tag{3.2}
\end{align*}
$$

where
(a) $w_{1}, w_{2}, h \in C(B)$.
(b) $w_{1}, w_{2}$ never vanish on $B$.
(c) $h$ is $1-1$ on $B$.

Note that we are claiming that it is possible to choose $h$ without any singularity. This is not possible if $B=S^{1}$.

Theorem 3.2. Assume $U_{n}$ and $V_{m}$ are $n$ - and m-dimensional Haar spaces in $C\left(S^{1}\right)$, respectively, $n$, $m$ odd, $n, m \geqslant 2$, and $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$. Then we can write $U_{n}$ and $V_{m}$ in the form

$$
\begin{align*}
U_{n} & =\operatorname{span}\left\{w_{1} h^{i-1}: i=1, \ldots, n\right\}  \tag{3.3}\\
V_{m} & =\operatorname{span}\left\{w_{2} h^{i-1}: i=1, \ldots, m\right\} \tag{3.4}
\end{align*}
$$

where
(a) $w_{1}, w_{2} \in C\left(S^{1}\right)$.
(b) There exists one point $x^{*} \in S^{1}$ such that $w_{1}\left(x^{*}\right)=w_{2}\left(x^{*}\right)=0$, and $w_{1}, w_{2}$ are strictly positive at all other points of $S^{1}$.
(c) $h$ is continuous and strictly increasing on $S^{1} \backslash\left\{x^{*}\right\}$, and the range of $h$ is all of $\mathbb{R}$; i.e., $\lim _{x \rightarrow x^{*-}} h(x)=\infty, \lim _{x \rightarrow x^{*+}} h(x)=-\infty$.

Furthermore, up to multiplication by constants and the choice of $x^{*}$, properties (a), (b), and (c) hold for all $w_{1}, w_{2}$ and $h$ satisfying (3.3) and (3.4).

Remark. Our abuse of mathematical precision in (c) should be understood thus. Let

$$
S^{1}=\left\{e^{i \theta}: \theta \in \mathbb{R}\right\}
$$

and $x^{*}=e^{i \theta^{*}}$. The function $h\left(e^{i \theta}\right)$ is continuous and strictly increasing as a function of $\theta$ on $\left(\theta^{*}, \theta^{*}+2 \pi\right)$, and its range thereon is all of $\mathbb{R}$.

Proof of Theorem 3.1. Based on Theorem 1.6 and the Haar space property, we first prove some preliminary facts which will also be used in the proof of Theorem 3.2.

Assume $w_{1}\left(x^{*}\right)=0$. Since $U_{n}$ is a Haar space there must exist some $u \in U_{n}$ for which $u\left(x^{*}\right) \neq 0$. This implies, see the remark near the end of Section 2, that $\left(w_{1} h^{i-1}\right)\left(x^{*}\right)=0, \quad i=1, \ldots, n-1$, and $\left(w_{1} h^{n-1}\right)\left(x^{*}\right) \neq 0$.

Thus $\lim _{x \rightarrow x^{*}}\left|h\left(x^{*}\right)\right|=\infty$, which in turn implies that $w_{2}\left(x^{*}\right)=0$. Hence $w_{1}$ and $w_{2}$ share the same zero set.

Now assume $w_{1}\left(x^{*}\right)=w_{1}(\tilde{x})=0$ for some $x^{*} \neq \tilde{x}$. But then $\left(w_{1} h^{i-1}\right)\left(x^{*}\right)$ $=\left(w_{1} h^{i-1}\right)(\tilde{x})=0, i=1, \ldots, n-1$, which implies that

$$
\left.\operatorname{dim} U_{n}\right|_{\left\{x^{*}, \tilde{x}\right\}}=1
$$

This contradicts the Haar space property of $U_{n}$. Thus $w_{1}$ and $w_{2}$ have at most one zero, and if it exists, it is a common zero.

Let $x_{1}, \ldots, x_{n}$ be $n$ distinct points in $B$, not including $x^{*}$ the zero of $w_{1}$, if such a point exists. Then from the Haar space property of $U_{n}$,

$$
0 \neq \operatorname{det}\left(\left(w_{1} h^{i-1}\right)\left(x_{j}\right)\right)_{i, j=1}^{n} .
$$

We can easily calculate the above Vandermonde type determinant. It equals

$$
\left[\prod_{j=1}^{n} w_{1}\left(x_{j}\right)\right] \prod_{1 \leqslant j<k \leqslant n}\left(h\left(x_{k}\right)-h\left(x_{j}\right)\right) .
$$

Thus $h$ is $1-1$ on $B$.
Now let us assume that $B$ is a finite union of closed disjoint intervals of $\mathbb{R}$ (none of which is a singleton). $h$ is continuous on the set where $w_{1}$ (or $w_{2}$ ) does not vanish. Thus if $w_{1}$ does not vanish on $B$, then $h$ is both continuous and $1-1$ on $B$ and Theorem 3.1 is proved. Assume there exists an $x^{*} \in B$ such that $w_{1}\left(x^{*}\right)=w_{2}\left(x^{*}\right)=0$. We claim that the range of $h$ cannot be all of $\mathbb{R}$. Since $h$ is continuous and 1-1 on $B \backslash\left\{x^{*}\right\}$ it follows that on each disjoint closed interval of $B$, the range of $h$ is a finite closed interval, except on the interval containing $x^{*}$. On that interval the range of $h$ will be $(-\infty, a]$, or $[b, \infty)$, or $(-\infty, a] \cup[b, \infty)$ for some $a<b$. These intervals (ranges) must all be disjoint (since $h$ is $1-1$ ) and thus cannot cover all of $\mathbb{R}$.

Choose $d \notin$ range $h$ and set

$$
H(x)=\frac{1}{h(x)-d}, \quad x \in B
$$

From Lemma 2.7, it follows that there exist $W_{1}, W_{2}$ such that

$$
\begin{aligned}
& U_{n}=\operatorname{span}\left\{W_{1} H^{i-1}: i=1, \ldots, n\right\} \\
& V_{m}=\operatorname{span}\left\{W_{2} H^{i-1}: i=1, \ldots, m\right\} .
\end{aligned}
$$

At no point $\tilde{x} \in B$ does $\lim _{x \rightarrow \tilde{x}}|H(x)|=\infty$. Thus $W_{1}$ and $W_{2}$ do not vanish on $B$ and (a), (b), and (c) necessarily hold.

Proof of Theorem 3.2. From the proof of Theorem 3.1 we have that $w_{1}$, $w_{2} \in C\left(S^{1}\right)$ have at most one (common) zero on $S^{1}$. If no such zero exists, then $h$ is $1-1$ and continuous on $S^{1}$. This is impossible since $h(0)=h(2 \pi)$. Thus there must exist a point $x^{*} \in S^{1}$ at which $w_{1}\left(x^{*}\right)=w_{2}\left(x^{*}\right)=0$. However, since there is only one such point in $S^{1}, w_{1}, w_{2}$ cannot change sign at this point; i.e., we may assume that both $w_{1}$ and $w_{2}$ are strictly positive at all other points. As $h$ is $1-1$ and continuous on $S^{1} \backslash\left\{x^{*}\right\}$ and $\lim _{x \rightarrow x^{*}}\left|h\left(x^{*}\right)\right|=\infty$, property (c) must hold for $h$ or $-h$.

The above properties hold (up to multiplication by a constant and the choice of $x^{*}$ ) for any $w_{1}, w_{2}$ and $h$ satisfying (3.3) and (3.4). This proves Theorem 3.2. Note that we may, replacing $h$ by

$$
H(x)=\frac{1}{h(x)-d},
$$

select the point $x^{*} \in S^{1}$ by an appropriate choice of $d \in \mathbb{R}$.
Remark. Theorems 3.1 and 3.2 embody the cases where $B$ is a compact set. However, this is not the only possible setting. For example, let $B=$ [ $0,2 \pi$ ) and let $U_{n}, V_{m} \subset C[0,2 \pi]$ be $n$ - and $m$-dimensional Haar subspaces on [ $0,2 \pi$ ), respectively, satisfying $u(0)=c u(2 \pi)$ for all $u \in U_{n}$, and $v(0)=d v(2 \pi)$ for all $v \in V_{m}, c, d \in \mathbb{R} \backslash\{0\}$. Assume $\operatorname{dim}\left(U_{n} V_{m}\right)=n+m-1$. What can we say about $U_{n}$ and $V_{m}$ ? (If $c=d=1$, then we refer to Theorem 3.2.) It follows from the Haar space property that if $c>0$, then $n$ is odd, while if $c<0$, then $n$ is even. From Theorem 1.6, $U_{n}$ and $V_{m}$ have the form

$$
\begin{aligned}
& U_{n}=\operatorname{span}\left\{w_{1} h^{i-1}: i=1, \ldots, n\right\} \\
& V_{m}=\operatorname{span}\left\{w_{2} h^{i-1}: i=1, \ldots, m\right\} .
\end{aligned}
$$

From an analysis similar to that in the above proofs of Theorems 3.1 and 3.2 one can prove that $w_{1}, w_{2} \in C[0,2 \pi], w_{1}(0)=c w_{1}(2 \pi), w_{2}(0)=$ $d w_{2}(2 \pi)$, and there exists exactly one point $x^{*} \in[0,2 \pi)$ for which $w_{1}\left(x^{*}\right)=$ $w_{2}\left(x^{*}\right)=0$ (this point may be chosen). If $x^{*} \in(0,2 \pi)$, then $w_{1}$, resp. $w_{2}$, does not change sign at $x^{*}$ if $c>0$, resp. $d>0$, and does change sign at $x^{*}$ if $c<0$, resp. $d<0 . h$ is continuous on [ $0,2 \pi) \backslash\left\{x^{*}\right\}$ and may be chosen to be strictly increasing on $[0,2 \pi) \backslash\left\{x^{*}\right\}$. $h$ also satisfies $h(0)=h(2 \pi)$, and the range of $h$ is all of $\mathbb{R}$.

Remark. From Theorems 3.1 and 3.2 it easily follows that if $u \in U_{n}$ and $v \in V_{m}$ have a common zero, then it can be factored out. (In the situation of Theorem 3.2 we can always assume that the common zero of $u$ and $v$ is not the common zero of $w_{1}$ and $w_{2}$ as this latter zero may be freely selected.) That is, if $u(\tilde{x})=v(\tilde{x})=0$, then $h-h(\tilde{x})$ divides both $u$ and $v$ (and the
numerator and denominator remain within $U_{n}$ and $V_{m}$, respectively). This implies, see for example Cheney [4, Chap. 5, Sect. 2], that $U_{n} / V_{m}$ is an existence set for $C(B)$. By that we mean that to every $f \in C(B)$ there exists a best approximant from $U_{n} / V_{m}$. This should be emphasized. In the Introduction (see Theorem 1.1 and Proposition 1.2) we always considered $r^{*}$ a best approximant from $U_{n} / V_{m}$. We purposely did not consider the possibility that a best approximation exists from the (correct) closure of $U_{n} / V_{m}$, but not from $U_{n} / V_{m}$ itself. This cannot occur here. The above form of $U_{n}$ and $V_{m}$ implies that every best approximant to any $f \in C(B)$ from the (correct) closure of $U_{n} / V_{m}$ can in fact be written as an element of $U_{n} / V_{m}$ (as long as in the situation of Theorem 3.2 we consider a form where the common zero of $u$ and $v$ is not the common zero of $w_{1}$ and $w_{2}$ ).

Proof of Theorem 1.5. We will prove that for each $r^{*} \in U_{n} / V_{m}$, the subspace $U_{n}+r^{*} V_{m} \subset C(B)$ is a Haar space. From Proposition 1.2 this proves the uniqueness property of $U_{n} / V_{m}$. We divide the proof into the two cases delineated by Theorems 3.1 and 3.2.

We first assume that the conditions of Theorem 3.1 hold; i.e., $B$ is not homeomorphic to $S^{1}$, and $U_{n}$ and $V_{m}$ are as given in (3.1) and (3.2). This is the simpler case and we essentially follow the proof given in Cheney [4, Chap. 5, Sect. 3].

If $u=w_{1}\left(\sum_{i=1}^{k} a_{i} h^{i-1}\right), a_{k} \neq 0$, then we say $u$ has degree $k-1$ and set $\partial u=k-1$. Thus, for example, $\partial\left(w_{1}\right)=0$. We do the same for $v \in V_{m}$. (Set $\partial 0=-\infty$ and by convention assume that if $r^{*}=u^{*} / v^{*}=0$, then $\partial u^{*}=-\infty$ and $\partial v^{*}=0$.)

We shall prove that with this notation, and for any $r^{*}=u^{*} / v^{*} \in U_{n} / V_{m}$ in irreducible form (no common factors of $h$ ), $U_{n}+r^{*} V_{m}$ is a Haar space of dimension

$$
\max \left\{n+\partial v^{*}, m+\partial u\right\} .
$$

The case $r^{*}=0$ is trivial and as such we assume $r^{*} \neq 0$. We first prove the dimension formula. We have

$$
\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right)=\operatorname{dim}\left(U_{n}\right)+\operatorname{dim}\left(r^{*} V_{m}\right)-\operatorname{dim}\left(U_{n} \cap r^{*} V_{m}\right),
$$

where $\operatorname{dim}\left(U_{n}\right)=n, \operatorname{dim}\left(r^{*} V_{m}\right)=m$. We must thus calculate $\operatorname{dim}\left(U_{n} \cap\right.$ $\left.r^{*} V_{m}\right)$. Let $u^{*}=w_{1}\left(\sum_{i=1}^{k} a_{i}^{*} h^{i-1}\right), a_{k}^{*} \neq 0$, and $v^{*}=w_{2}\left(\sum_{i=1}^{l} b_{i}^{*} h^{i-1}\right)$, $b_{\ell}^{*} \neq 0$, with no common factors. Thus $k=\partial u^{*}+1$ and $\ell=\partial v^{*}+1$. Now

$$
\begin{aligned}
r^{*} V_{m} & =\left\{\frac{u^{*}}{v^{*}} v: v \in V_{m}\right\} \\
& =\left\{\frac{w_{1}\left(\sum_{i=1}^{k} a_{i}^{*} h^{i-1}\right)}{\left(\sum_{i=1}^{\ell} b_{i}^{*} h^{i-1}\right)}\left(\sum_{i=1}^{m} c_{i} h^{i-1}\right): c_{1}, \ldots, c_{m} \in \mathbb{R}\right\} .
\end{aligned}
$$

As $u^{*}$ and $v^{*}$ have no common factors, in order for $u^{*} v / v^{*}, v \in V_{m}$, to be an element of $U_{n}$ it is necessary (and sufficient) that $v$ factor in the form

$$
v=v^{*}\left(\sum_{i=1}^{s} d_{i} h^{i-1}\right)
$$

with arbitrary $d_{1}, \ldots, d_{s} \in \mathbb{R}$ and with certain restrictions on $s$. What are these restrictions? A simple counting shows that in order for $v \in V_{m}$ we need $s \leqslant m-\partial v^{*}$, while in order that $u^{*} v / v^{*} \in U_{n}$ we need $s \leqslant n-\partial u^{*}$. Thus

$$
\operatorname{dim}\left(U_{n} \cap r^{*} V_{m}\right)=\min \left\{m-\partial v^{*}, n-\partial u^{*}\right\}
$$

and

$$
\begin{aligned}
\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right) & =n+m-\min \left\{m-\partial v^{*}, n-\partial u^{*}\right\} \\
& =\max \left\{n+\partial v^{*}, m+\partial u^{*}\right\} .
\end{aligned}
$$

It remains to prove that $U_{n}+r^{*} V_{m}$ is a Haar space. This follows from the form of $U_{n}+r^{*} V_{m}$. For any $u \in U_{n}, v \in V_{m}$, the zero set of $u+r^{*} v$ is identical to that of $u v^{*}+u^{*} v$, since we have assumed that $v^{*}$ does not vanish on $B$. Now

$$
\begin{aligned}
u v^{*} & +u^{*} v \\
& =w_{1} w_{2}\left[\left(\sum_{i=1}^{n} c_{i} h^{i-1}\right)\left(\sum_{i=1}^{\ell} b_{i}^{*} h^{i-1}\right)+\left(\sum_{i=1}^{k} a_{i}^{*} h^{i-1}\right)\left(\sum_{i=1}^{m} d_{i} h^{i-1}\right)\right] \\
& =w_{1} w_{2}\left[\sum_{i=1}^{s} \alpha_{i} h^{i-1}\right]
\end{aligned}
$$

where $s \leqslant \max \left\{n+\partial v^{*}, m+\partial u^{*}\right\}=\operatorname{dim}\left(U_{n}+r^{*} V_{m}\right)$. Since $w_{1}, w_{2}$ do not vanish on $B$, and $h$ is $1-1$ thereon, no nonzero function of the above form has more than $s-1$ distinct zeros in $B$. Thus $U_{n}+r^{*} V_{m}$ is a Haar space.

We now assume that the conditions of Theorem 3.2 hold; i.e., $B$ is homeomorphic to $S^{1}$, and $U_{n}$ and $V_{m}$ are as given in (3.3) and (3.4). This is the more interesting case.

As previously, we assume that $r^{*}=u^{*} / v^{*} \neq 0$ is in irreducible form (no common factors of $h$ ) and we will prove that $U_{n}+r^{*} V_{m}$ is a Haar space. Again we assume that $v^{*}$ does not vanish on $B$. Previously this was well understood, and presented no problem. However as $w_{1}$ and $w_{2}$ vanish at some point, and $|h|$ tends to infinity at this same point, we should explain what is meant here. We simply assume that $u^{*} / v^{*}$ is well defined (and thus finite) at each point of $B$. This imposes certain conditions.

Assume $w_{1}\left(x^{*}\right)=w_{2}\left(x^{*}\right)=0$ and $u^{*} / v^{*}$ does not vanish at $x^{*}$. Let

$$
u^{*}=w_{1}\left(\sum_{i=1}^{k} a_{i}^{*} h^{i-1}\right), \quad a_{k}^{*} \neq 0
$$

and

$$
v^{*}=w_{2}\left(\sum_{i=1}^{\ell} b_{i}^{*} h^{i-1}\right), \quad b_{\ell}^{*} \neq 0 .
$$

Then

$$
\lim _{x \rightarrow x^{*}} \frac{u^{*}(x)}{v^{*}(x)}=\lim _{x \rightarrow x^{*}} \frac{w_{1}(x) a_{k}^{*} h^{k-1}(x)}{w_{2}(x) b_{\ell}^{*} h^{\ell-1}(x)}=\frac{a_{k}^{*}}{b_{\ell}^{*}} \lim _{x \rightarrow x^{*}} \frac{w_{1}(x)}{w_{2}(x)} h^{k-\ell}(x) .
$$

From (3.3) and (3.4), $\lim _{x \rightarrow x^{*}} w_{1}(x) h^{n-1}(x)$ and $\lim _{x \rightarrow x^{*}} w_{2}(x) h^{m-1}(x)$ both exist and are non-zero. Thus

$$
\lim _{x \rightarrow x^{*}} \frac{w_{1}(x)}{w_{2}(x)} h^{n-m}(x)
$$

exists and is nonzero. As we assume that

$$
\lim _{x \rightarrow x^{*}} \frac{u^{*}(x)}{v^{*}(x)}
$$

exists and is nonzero, we must have $k-\ell=n-m$. If $u^{*} / v^{*}$ vanishes at $x^{*}$, then we obtain $k-\ell \leqslant n-m$. In either case $m+k \leqslant n+\ell$, i.e., $m+\partial u^{*} \leqslant$ $n+\partial v^{*}$.

In addition,

$$
\begin{equation*}
v^{*}=w_{2}\left(\sum_{i=1}^{\ell} b_{i}^{*} h^{i-1}\right)=w_{2} \beta \prod_{j=1}^{\ell-1}\left(h-\gamma_{j}\right) \tag{3.5}
\end{equation*}
$$

for some $\beta \neq 0$. As the range of $h$ is all of $\mathbb{R}$, it follows that if $\gamma_{j}$ is real, then $v^{*}$ has a zero in $B$ at some point $\tilde{x}$, other than $x^{*}$, where $h(\tilde{x})=\gamma_{j}$. For $u^{*} / v^{*}$ to be well-defined and finite at $\tilde{x}$ it is therefore necessary that $u^{*}(\tilde{x})=0$. But then $\left(h-\gamma_{j}\right)$ is a common factor of $u^{*}$ and $v^{*}$ contradicting our assumption that they have no common factors. (We also contradict our assumption that $v^{*}$ does not vanish on $B$.) This implies that each $\gamma_{j}$ in (3.5) is in $\mathbb{C} \backslash \mathbb{R}$. As the $b_{i}^{*}$ are real, these nonreal roots of $v^{*}$ come in complex conjugate pairs. Thus

$$
v^{*}=w_{2} \beta \prod_{j=1}^{s}\left(h-\delta_{j}\right)\left(h-\bar{\delta}_{j}\right)
$$

for $\delta_{j} \notin \mathbb{R}$. Therefore $\ell-1=2 s$, i.e., $\partial v^{*}=\ell-1=2 s$ (is necessarily even) and hence $n+\partial v^{*}$ is odd.

With the above facts we can now parallel the previous proof and show that $U_{n}+r^{*} V_{m}$ is a Haar space of dimension $n+\partial v^{*}$.

## 4. TRIGONOMETRIC POLYNOMIALS

Let

$$
T_{n}=\operatorname{span}\{1, \sin x, \cos x, \ldots, \sin n x, \cos n x\} .
$$

$T_{n}$ is a periodic Haar space of dimension $2 n+1$ on $[0,2 \pi)$. It is the prototype of a Haar space on $B$, where $B$ is homeomorphic to $S^{1} . T_{n}$ (together with $T_{m}$ ) satisfy the assumptions of Theorem 3.2. If $w(x)=$ $1-\cos x$ and $h(x)=\sin x /(1-\cos x)$, then it may be easily calculated that

$$
\begin{equation*}
T_{n}=\operatorname{span}\left\{w^{n} h^{i-1}: i=1, \ldots, 2 n+1\right\} . \tag{4.1}
\end{equation*}
$$

This is a non-standard (but useful) basis for $T_{n}$. It may also be rewritten as follows. Recall that $1-\cos x=2 \sin ^{2}(x / 2)$ and $\sin x=2 \sin (x / 2) \cos (x / 2)$. Thus

$$
h(x)=\frac{\sin x}{1-\cos x}=\frac{\cos (x / 2)}{\sin (x / 2)}
$$

and up to a constant

$$
w^{n} h^{i-1}=(\sin (x / 2))^{2 n-i+1}(\cos (x / 2))^{i-1}, \quad i=1, \ldots, 2 n+1,
$$

i.e.,

$$
T_{n}=\operatorname{span}\left\{(\sin (x / 2))^{2 n-i}(\cos (x / 2))^{i}: i=0,1, \ldots, 2 n\right\} .
$$

For $t \in T_{p} \backslash T_{p-1}$, let $\tilde{\partial} t=2 p$. (Set $\tilde{\partial} 0=-\infty, \tilde{\partial} 1=0$.). This differs from the $\partial t$ as defined in the proof of Theorem 1.5, and it is this difference which we now discuss. In Lorentz et al. [8, p. 217] it is proven that for $r^{*}=u^{*} / v^{*} \in T_{n} / T_{m}$

$$
\operatorname{dim}\left(T_{n}+r^{*} T_{m}\right)=\max \left\{2 n+1+\widetilde{\partial} v^{*}, 2 m+1+\tilde{\partial} u^{*}\right\} .
$$

On the other hand we have proved that

$$
\operatorname{dim}\left(T_{n}+r^{*} T_{m}\right)=2 n+1+\partial v^{*}
$$

(and $2 n+1+\partial v^{*} \geqslant 2 m+1+\partial u^{*}$ ). It must be that these two quantities are the same. But why?

One explanation is the following. Assume that we have chosen the basis

$$
T_{n}=\operatorname{span}\left\{w^{n} h^{i-1}: i=1, \ldots, 2 n+1\right\},
$$

where the $w$ and $h$ are as in (4.1). We further assume, without great loss of generality, that $r^{*}(0) \neq 0$ (here $x^{*}=0$ ).

Let

$$
\begin{array}{ll}
u^{*}=w^{n}\left(\sum_{i=1}^{k} a_{i}^{*} h^{i-1}\right), & a_{k}^{*} \neq 0 \\
v^{*}=w^{m}\left(\sum_{i=1}^{\ell} b_{i}^{*} h^{i-1}\right), & b_{\ell}^{*} \neq 0 .
\end{array}
$$

It was shown in the proof of Theorem 1.5 that $k-\ell=2 n-2 m$, and $\partial v^{*}=\ell-1=2 s$. Thus $\partial u^{*}=k-1=2 q$ and $2 n+1+\partial v^{*}=2 m+1+\partial u^{*}$. (If $r^{*}(0)=0$, then we obtain $2 n+1+\partial v^{*} \geqslant 2 m+1+\partial u^{*}$.)

Every $t \in T_{p}$ may be written in the form

$$
\begin{equation*}
t=w^{p} \sum_{i=1}^{2 p+1} c_{i}^{*} h^{i-1} . \tag{4.2}
\end{equation*}
$$

Moreover since $t \in T_{n}$ for every $n>p$, it may also be written in the form

$$
\begin{equation*}
t=w^{n} \sum_{i=1}^{2 n+1} c_{i, h}^{*} h^{i-1}, \tag{4.3}
\end{equation*}
$$

for some unique choice of $c_{i, n}^{*}$. How are the forms (4.2) and (4.3) related?
It is easily checked that

$$
1=\frac{w}{2}\left(1+h^{2}\right) .
$$

Thus from the uniqueness of the coefficients in (4.2) and (4.3) we must have (as a function of $h$ )

$$
\sum_{i=1}^{2 n+1} c_{i, n}^{*} h^{i-1}=\left(\sum_{i=1}^{2 p+1} c_{i}^{*} h^{i-1}\right)\left(\frac{1+h^{2}}{2}\right)^{n-p}
$$

for each $n>p$. This is how (4.2) and (4.3) are related.
We now return to $u^{*}$ and $v^{*}$. By assumption $u^{*}$ and $v^{*}$ have no common factors of $h$. From the above analysis it therefore follows that either $\partial u^{*}=$ $\tilde{\partial} u^{*}$ and $\partial v^{*} \geqslant \tilde{\partial} v^{*}$, or $\partial u^{*} \geqslant \tilde{\partial} u^{*}$ and $\partial v^{*}=\tilde{\partial} v^{*}$. (The only other option is
that $\partial u^{*}>\tilde{\partial} u^{*}$ and $\partial v^{*}>\tilde{\partial} v^{*}$ in which case both $u^{*}$ and $v^{*}$ contain common positive powers of $\left(1+h^{2}\right)$.) Furthermore we recall that $2 n+1+\partial v^{*}$ $=2 m+1+\partial u^{*}$. Thus

$$
\max \left\{2 n+1+\tilde{\partial} v^{*}, 2 m+1+\widetilde{\partial} u^{*}\right\}=2 n+1+\partial v^{*} .
$$

If $r^{*}(0)=0$, then the same final result holds.
Remark. The space

$$
C_{n}=\operatorname{span}\{1, \cos x, \ldots, \cos n x\}
$$

has the form

$$
C_{n}=\operatorname{span}\left\{w h^{i-1}: i=1, \ldots, n+1\right\},
$$

where $w=1$ and $h=\cos x$. It is a Haar space of dimension $n+1$ on $[0, \pi]$. The space

$$
S_{n}=\operatorname{span}\{\sin x, \ldots, \sin n x\}
$$

also has the form

$$
S_{n}=\operatorname{span}\left\{w h^{i-1}: i=1, \ldots, n\right\} .
$$

Here $w=\sin x$ and $h=\cos x$. It is a Haar space of dimension $n$ on $(0, \pi)$. Note that since $C_{n}$ and $S_{m}$ share a common $h$ we have $\operatorname{dim}\left(C_{n} S_{m}\right)=n+m$. It follows (most easily using the above bases) that $C_{n} S_{m}=S_{n+m}$. Similarly $C_{n} C_{m}=C_{n+m}$, while $S_{n} S_{m}=(\sin x) S_{n+m-1}$; i.e.,

$$
S_{n} S_{m}=\operatorname{span}\{\sin x \cdot \sin k x: k=1, \ldots, n+m-1\} .
$$

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